

# **PSA Scenario Modeling and Representation**

## **- a view based on dynamic PSA research**

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## Presentation Outline

- Some issues for PSA
- Dynamic PSA
  - Accident dynamics
  - The dynamic event tree
- Implications for PSA software, model portability and representation

## Some issues for PSA

- **Uncertainties**
  - ☑ aleatory and epistemic
- **Human Reliability Analysis**
  - ☑ decision-making performance
  - ☑ errors of commission

Also

- Procedure verification in PSA scenarios
- Digital systems (I&C) safety

## Aleatory and Epistemic Uncertainties

### Definitions:

- Aleatory: random or stochastic effects
  - ☑ e.g. hardware performance (e.g. failure to start, to open, close)
  - ☑ operator interventions
- Epistemic: state-of-knowledge
  - ☑ parameter uncertainty (TH coefficients, etc, **as well as** failure probabilities)
  - ☑ establishment of natural circulation
  - ☑ material behavior
  - ☑ severe accident phenomena
    - for some events and behaviors (e.g. last examples), the distinction is not clear-cut. Some events involve both types of uncertainties

## Human Reliability Analysis

- Decision-making performance
  - ☑ diagnosis failure probabilities, initially represented by Time Reliability Curves (TRCs, e.g. THERP curves: HEP vs. available time)
    - this model (and variants) continues to dominate HRAs, mainly due to lack of alternatives
  - ☑ less emphasis on time as the main driving factor
    - SLIM performance shaping factors (but calibration values required to “complete” the method)
    - CREAM, INEL’s SPAR-H
- ☑ **ultimately, two questions**
  - what factors should drive estimates of decision-making failures?
  - what about other decisions, i.e. errors of commission?

## Analyzing Errors of Commission (EOCs)

performance of any inappropriate action that aggravates the situation

Compare *omissions*: failure to perform a required action

### Identification

- What are plausible EOC situations?

How do we search efficiently, given that an aggravating action can potentially take place any time, in connection to any system?

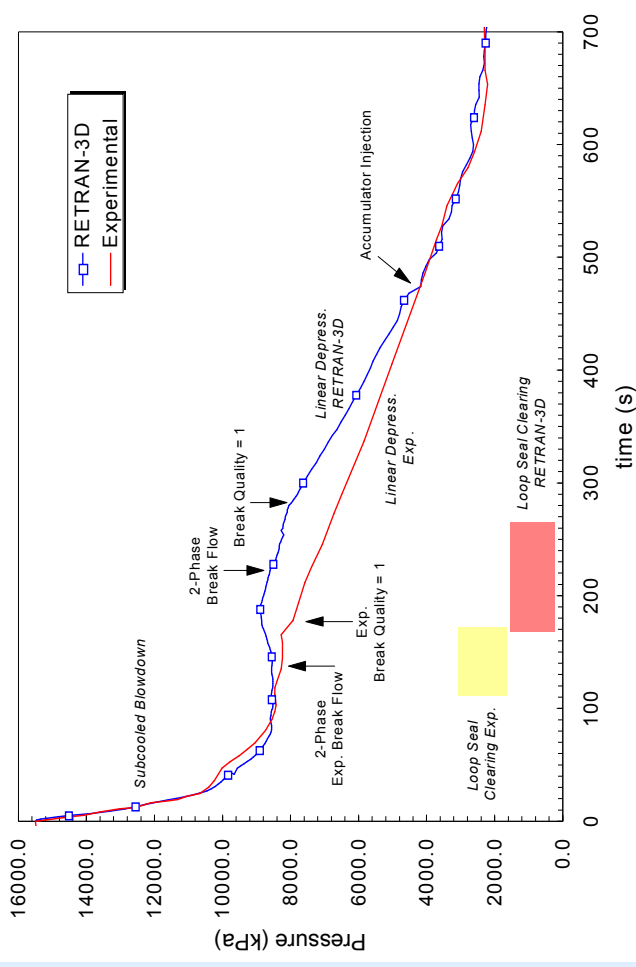
- Number of methods have emerged: MERMOS, ATHEANA, MDTA, CESA

### Quantification

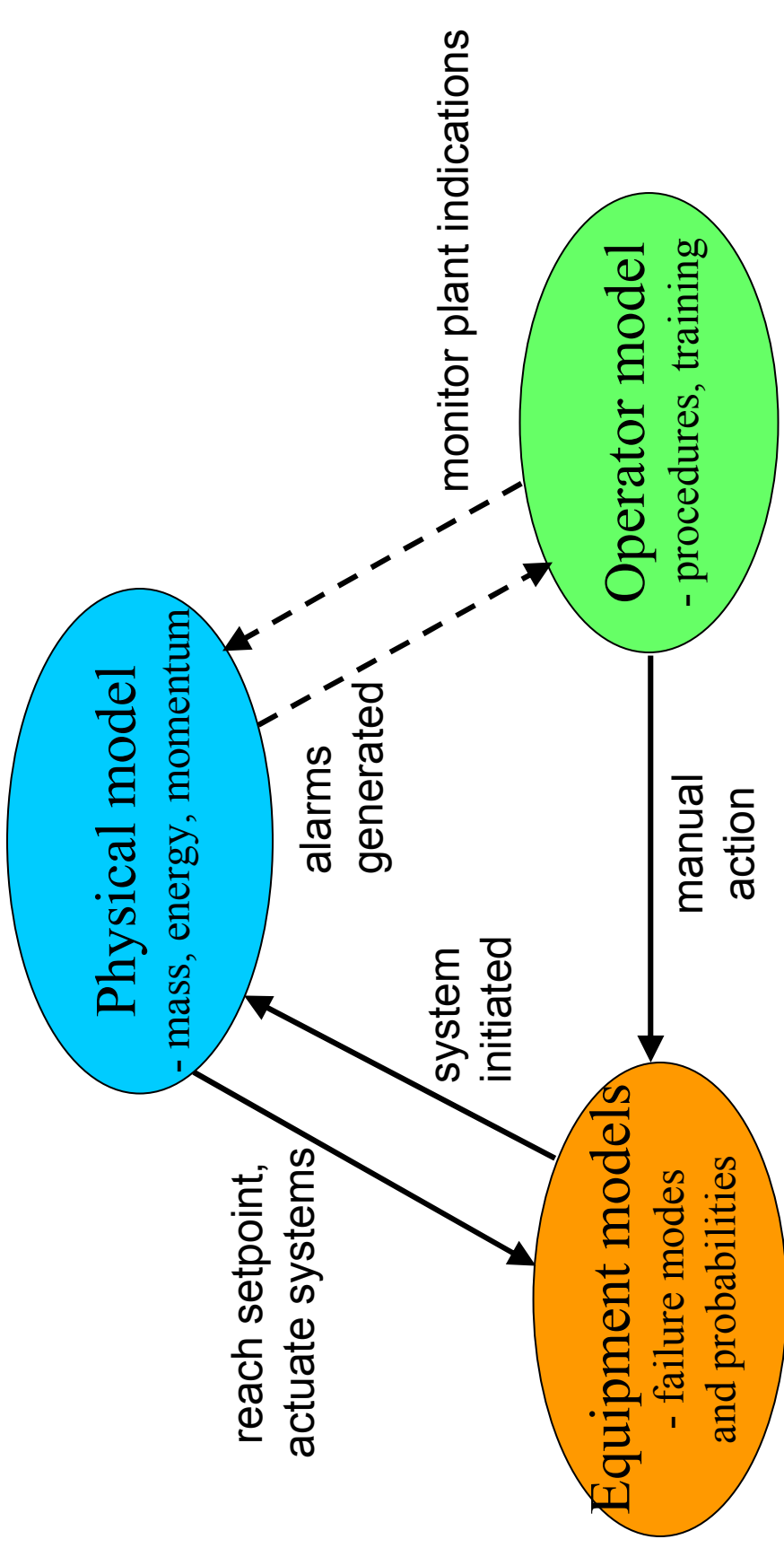
- Contexts where the EOC corresponds to the nominal, expected operator response, also referred to as “error-forcing”.
  - Once identified, can be handled
- ❑ Situations where the decision is more “uncertain” are more difficult.
  - Time pressure plays a role but a time reliability approach does not seem workable. Need to characterize “attractiveness” of multiple options
- ❑ Once EOC is performed, need to assess the probability of correction
  - Function of cues and time window

## Accident Scenarios – What dynamics, What interactions?

- **thermal-hydraulics and physics** : P, T, energy balances
  - ☑ heat removed during blowdown
  - ☑ amount of lost coolant
  - ☑ maximum temperatures
- **automatic system actions**
  - ☑ initiation and termination of systems
  - ☑ active and passive
- **operator actions** : procedures and training
  - ☑ initiation, termination, throttling
  - ☑ inhibit, reset, override
- **equipment failures**
  - ☑ to start (and while running)
  - ☑ cycling
  - ☑ support systems



## Dynamic interactions in accident scenarios





## Accident scenario analysis

### ➤ For design basis calculations

- ☑ Defined, bounding scenarios
- ☑ Few cases for each initiating event
- ☑ 0-1 operator actions in first 30 minutes, 1-3 subsequently
- ☑ Conservative scenarios

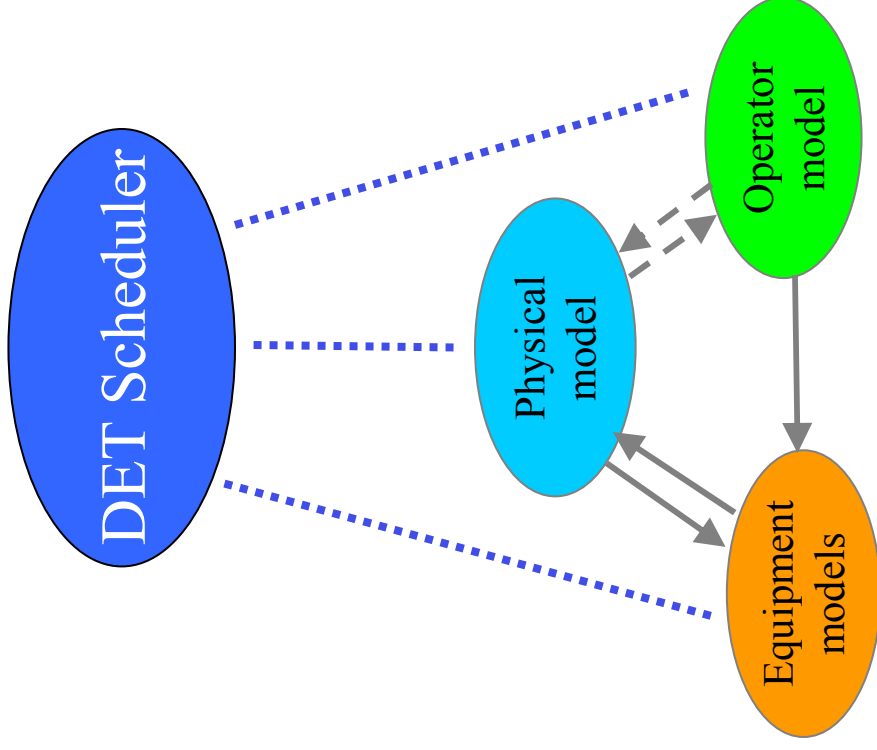
### ➤ For PSA

- ☑ Consider multiple failures and probabilities of scenarios
- ☑ Calculation of success criteria: minimum number of systems, minimum time of operation, latest time for interventions
- ☑ 2-6 cases per initiating event, supplemented by bounding calculations

### ➤ Integrated deterministic/probabilistic analysis

- ☑ Integration of deterministic (accident evolutions) and probabilistic perspectives (account for likelihood of failure events and distributions of occurrence times)
- ☑ Especially relevant for advanced and future reactor and plant designs (no artifacts from the “design basis” approach)

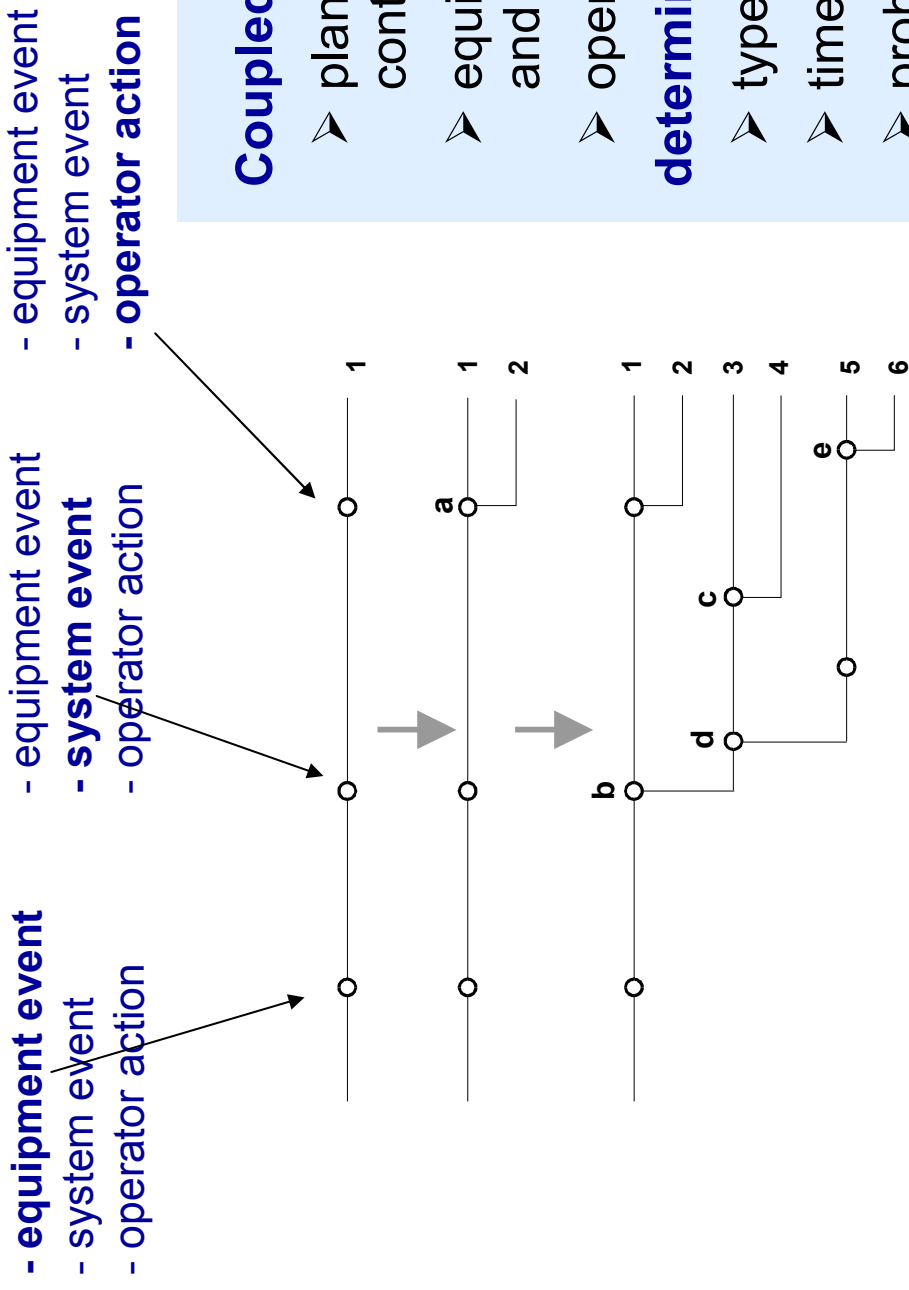
## Dynamic event trees – a framework for solving probabilistic dynamics



### Functions of the scheduler

- advance physical model solution
- respond to model events
  - ☑ setpoints and alarms
  - ☑ equipment demands
  - ☑ running failures
  - ☑ monitoring and manipulations
- question probabilistic events (equipment failures)
- set physical model boundary conditions
- probability accounting, truncation in background

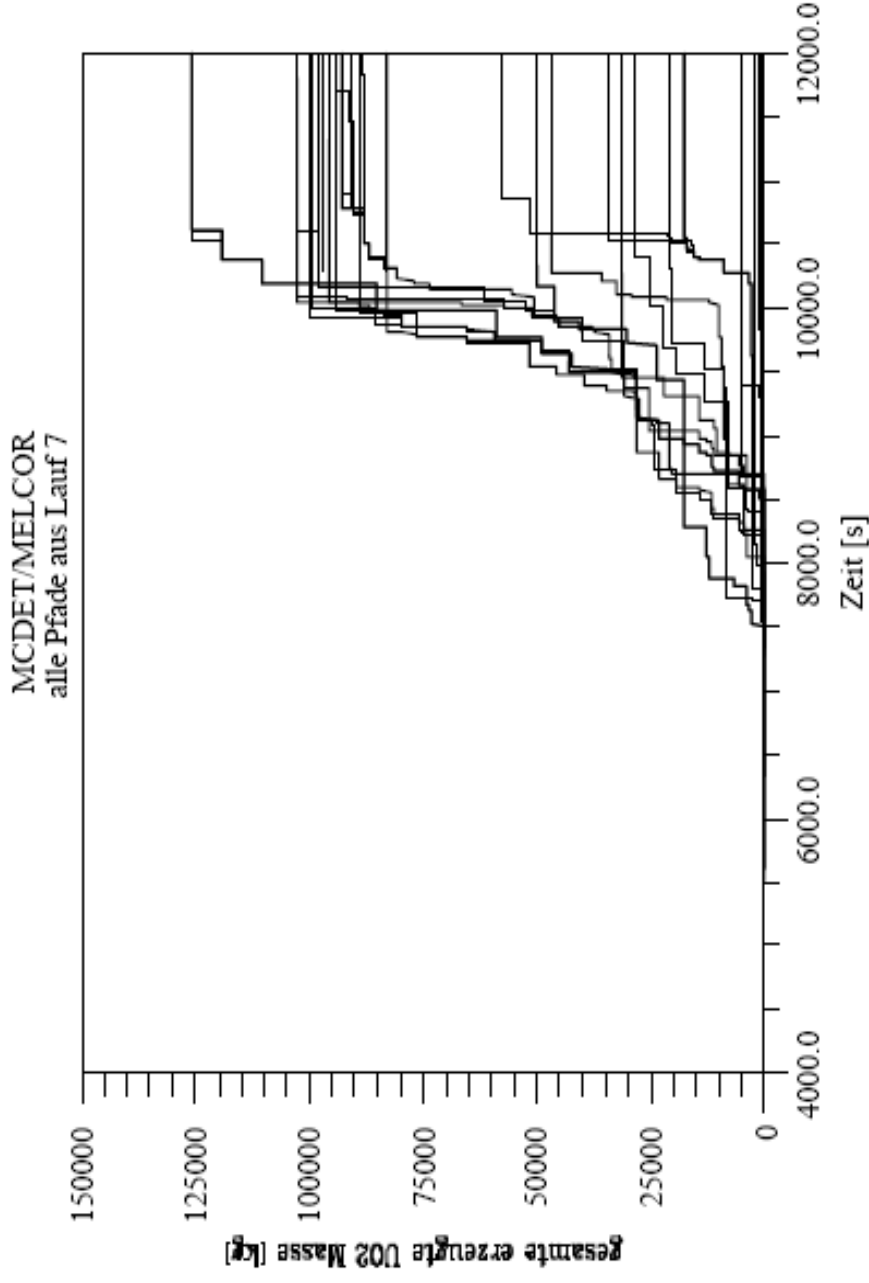
## The Discrete Dynamic Event Tree (DDET)



### Coupled models of

- plant dynamics and control
  - equipment availability, and
  - operator response
- determine...**
- type of event
  - time of event
  - probability of event

## Application of DET to a PRA level 2 problem (MCDET)

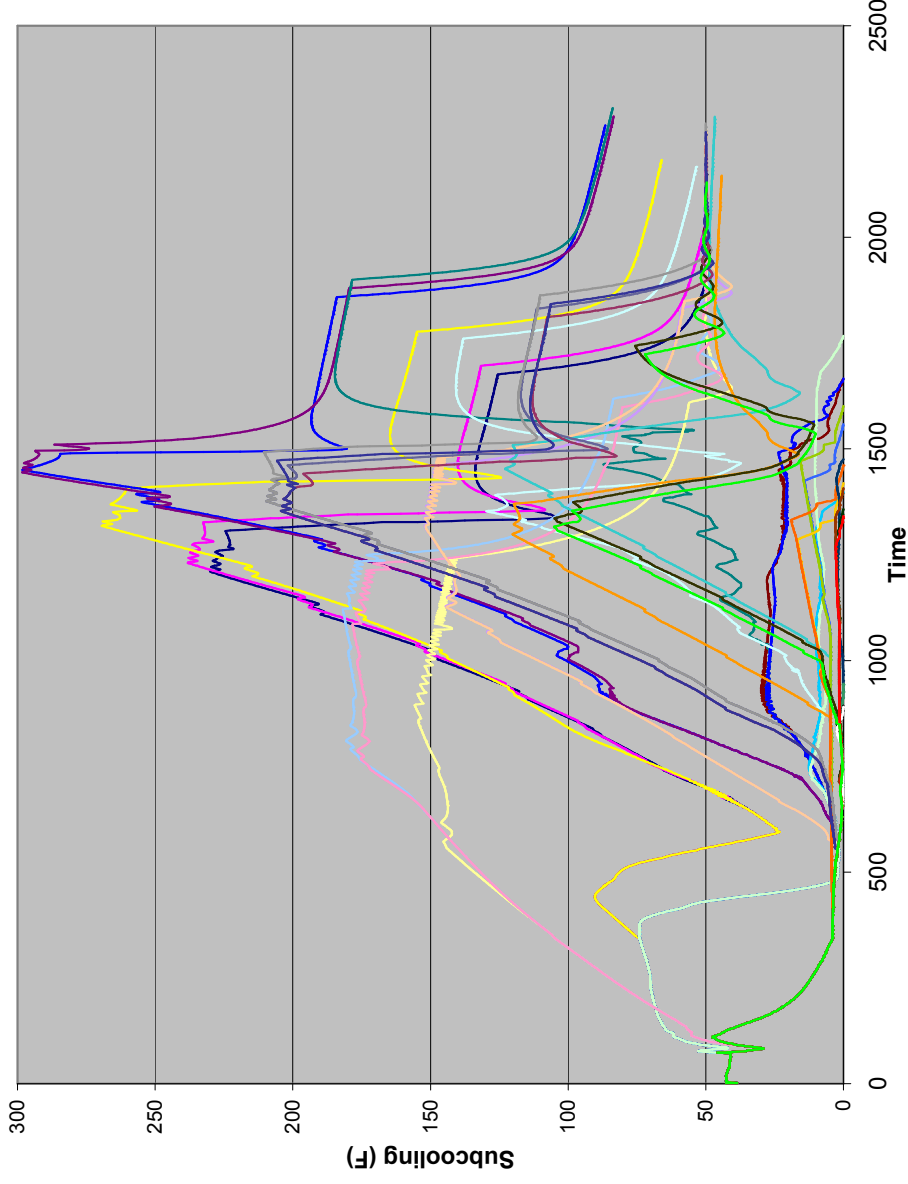


**Fig. 4:** Dynamic event tree no. 7 of the sample presented in the time/state plane for the state variable "total generated UO<sub>2</sub> melt mass"

**Hofer et al, 2002 (Eurosaf)**

## DET Results

### Subcooling Margin in SGTR Sequences



### 36 Sequences

- MSIVs open/closed
- HPI automatic start
- HPI manually started
  - based on training
  - guided by procedure
- variability in timing of operator response

## Conclusions (1 of 2)

- A number of different PSA issues motivate a dynamic PSA approach.
  - accident evolutions
    - in severe accident space (Level 2 PSA, e.g. passive components, creep rupture)
    - effect of partial failures, timing of failures on success criteria (Level 1)
  - analysis of decision-making and EOCs in Human Reliability Analysis
  - verification of procedures in PSA scenario space
- Large parts of the PSA continue to drive system unavailability and are therefore needed
  - support system dependencies
  - component failure data
  - common cause failures
  - latent system failures
  - maintenance and test unavailabilities

## Conclusions (2 of 2)

- In extending the safety analysis towards dynamic PSA, there is a motivation to re-use the models from existing PSAs
  - large models, fortunately relatively stable
  - quality-controlled
  - re-use allows comparison with “classical” ET/FT analysis
- Portability and clarity of the models and data compatibility are major issues.
- Besides supporting next generation calculation engines and user interfaces, progress along these lines will be crucial to the development of dynamic PSA
  - as software
  - as an analysis framework